

## Early Stage Safety Planning via Virtual Modelling The Pros and Cons of using mighty software





## AGENDA

Safety Integrated Simultaneous Engineering Safety Checks via "Process Simulate Human" Modell Based Calculation of Safety Reaction Times Reflections and Summary



#### Short Ramp Up Periods must also consider the Concerns of Safety!



→ Higher profits and earlier Start of Productions (SOP) need steeper ramp ups
→ Steeper ramp ups must not forget the finally necessary Safety Acceptance



#### Safety Planning also has to be a part of Simultanous Engineering





#### A shared Database and Digital Twins are a Must Have for doing an efficient Simultaneous Safety Engineering



→ Digital Twins of Products, Processes and Working Environments are essential

- → Seamless Data Integration is a prerequisite for doing ongoing simulations
- → The Human Expert cannot be replaced anyhow



#### The smartfactory@tugraz as a Learning Factory is a splendid research field for data integrated manufacturing



# SIEMENS PLM

- ➔ NX CAD
- ➔ NX CAE
- → NX CAM
- ➔ NX MCD
- ➔ TIA Portal
- → SIMIT Simulations Platform
- ➔ Process Simulate Human
- → .....

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Source: own representation



## **Creating Digital Twins of the Workplaces**





## **Creating Digital Twins of the whole Factory**



Real World

**Digital Twin** 



#### 2 Show Cases in Terms of Modelling Based Safety Planning

#### Safety and Ergonomic Analysis via Process Simulate - Human Advanced



Source: Siemens

#### **Measurement of Safety Reaction Times** via SIMIT Simulation SW



Source: Siemens + IFT

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#### The Simulation examines the Suitability of Safety Precautions



Simulation including folowing Safety Devices:

- ⇒ Safety Mat
- ⇒ Safety Curtain
- ⇒ Indicator Lamps



Source: own representation



#### **Actual Calculation of Safety Reaction Time**



**Actual Procedure:** 

Working with Time Tables of System Providers

Use of manifold Assumptions and Expert Recommendations



#### Model Based Calculation of Safety Reaction Times



Proprietary Control Unit always remains to be a secret: What is the robot really doing?

- → Established Simulation is based on the principle "Hardware in the Loop"
- → Complex Set up of HW and SW- Interfaces is required



#### Architecture for doing Simulations of the "Stäubli"-Robot Cell







CSi9 Control Unit

On this basis the Simulations definitely follow the commands of the proprietary Control Unit CSi9 of the Stäubli Robot !

Univ.-Prof. Dr. Rudolf Pichler

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#### Simulation Based Calculation of Safety Reaction Time





# Reflections on working with Virtual Models and Simulations in Safety Concerns

- © Working with virtual models of new production processe accelerate the ramp up dramatically. The early inclusion of safety Issues is not only possible but recommendable.
- © Such simulations do not only allow the early detection of failures modes but also give a quick response to engineered alternatives.
- There are high efforts in the build up and working phase of such virtual models. Target lead times and target costs could could easily make a stop.
- Sumulation results are not adequate for passing the Acceptance Tests. Series of physical measurements have to be done additionally. The questions of Liability often remain open.



#### Summary

The Future of Safety Planning

→ will increasingly be supported by virtual models

- $\rightarrow$  will be part of the simultaneous engineering processes
- → will work with standardized libraries and testing cycles
- $\rightarrow$  will still not replace the human expert

START SMALL, BUT START !

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## Thank you for your Attention!

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